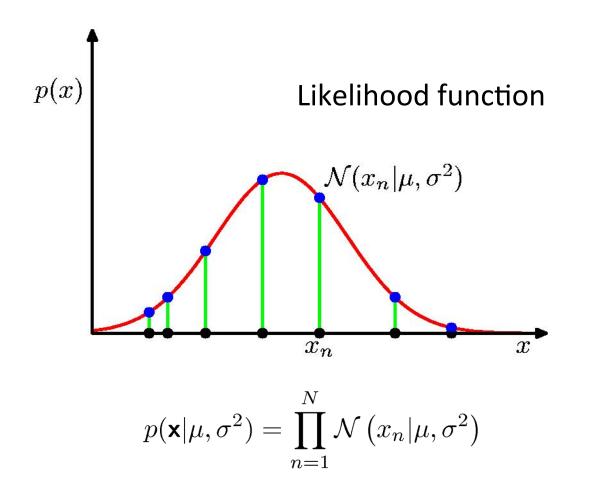
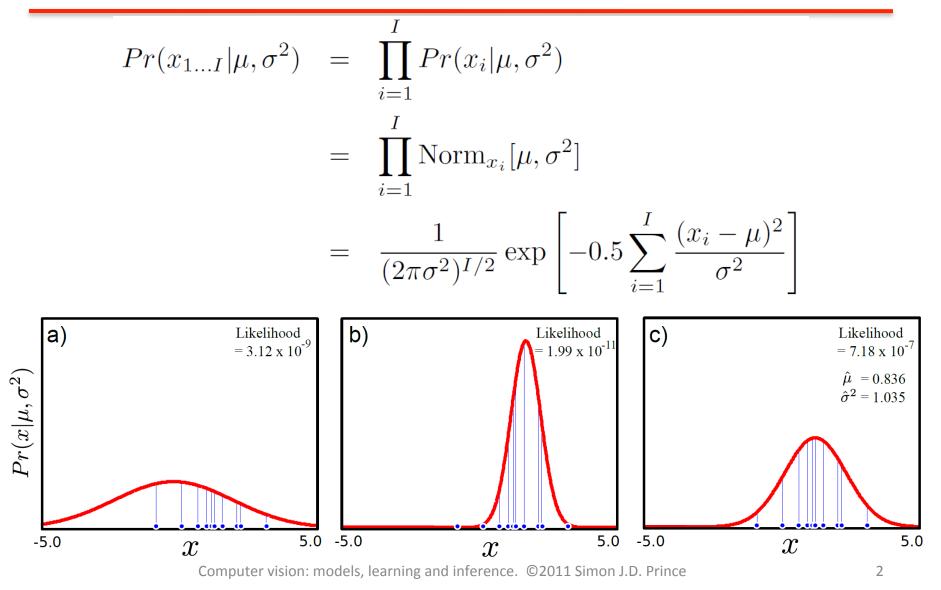
Gaussian Parameter Estimation

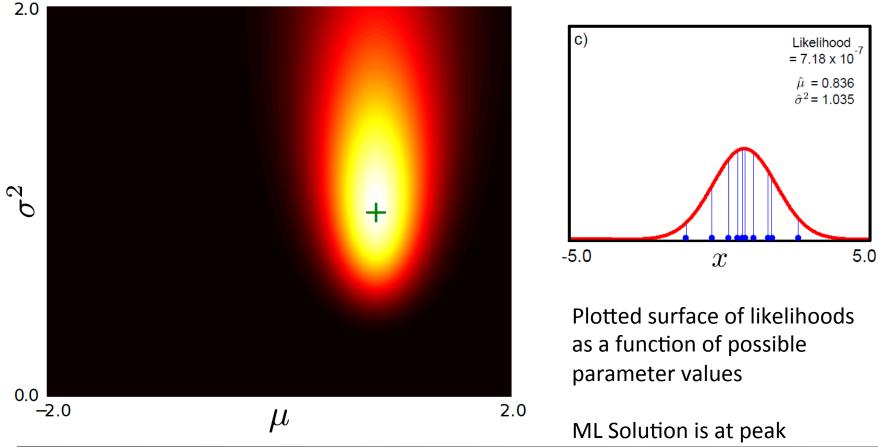


Fitting normal distribution: ML



Fitting a normal distribution: ML

 $Pr(x_{1...I}|\mu,\sigma^2)$



Bayesian Inference for the Gaussian (1)

Assume σ is known. Given i.i.d. data

 $\mathbf{x} = \{x_1, \dots, x_N\}$, the likelihood function for μ is given by

$$p(\mathbf{x}|\mu) = \prod_{n=1}^{N} p(x_n|\mu) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp\left\{-\frac{1}{2\sigma^2} \sum_{n=1}^{N} (x_n - \mu)^2\right\}.$$

This has a Gaussian shape as a function of μ (but it is *not* a distribution over μ).

Bayesian Inference for the Gaussian (2)

Combined with a Gaussian prior over μ ,

$$p(\mu) = \mathcal{N}\left(\mu|\mu_0, \sigma_0^2\right).$$

this gives the posterior

 $p(\mu|\mathbf{x}) \propto p(\mathbf{x}|\mu)p(\mu).$

Completing the square over μ , we see that $p(\mu|\mathbf{x}) = \mathcal{N}\left(\mu|\mu_N, \sigma_N^2\right)$

Bayesian Inference for the Gaussian (3)

... where

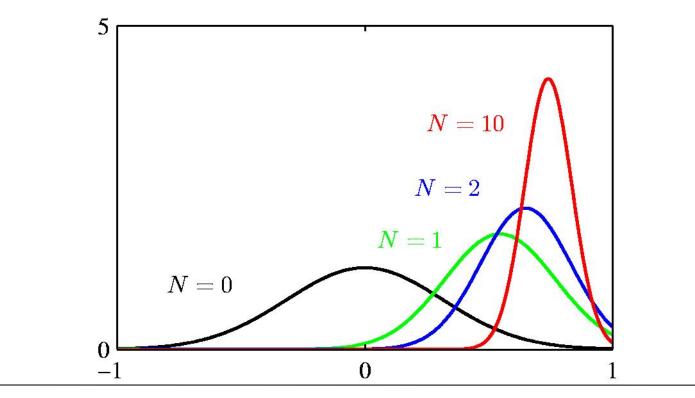
$$\mu_{N} = \frac{\sigma^{2}}{N\sigma_{0}^{2} + \sigma^{2}}\mu_{0} + \frac{N\sigma_{0}^{2}}{N\sigma_{0}^{2} + \sigma^{2}}\mu_{ML}, \qquad \mu_{ML} = \frac{1}{N}\sum_{n=1}^{N}x_{n}$$
$$\frac{1}{\sigma_{N}^{2}} = \frac{1}{\sigma_{0}^{2}} + \frac{N}{\sigma^{2}}.$$

Note:

	N = 0	$N \to \infty$
$\overline{ egin{array}{c} \mu_N \ \sigma_N^2 \end{array} }$	$egin{array}{c} \mu_0 \ \sigma_0^2 \end{array}$	${\mu_{ m ML} \over 0}$

Bayesian Inference for the Gaussian (4)

Example: $p(\mu|\mathbf{x}) = \mathcal{N}(\mu|\mu_N, \sigma_N^2)$ for N = 0, 1, 2 and 10.



Bayesian Inference for the Gaussian (5)

Sequential Estimation

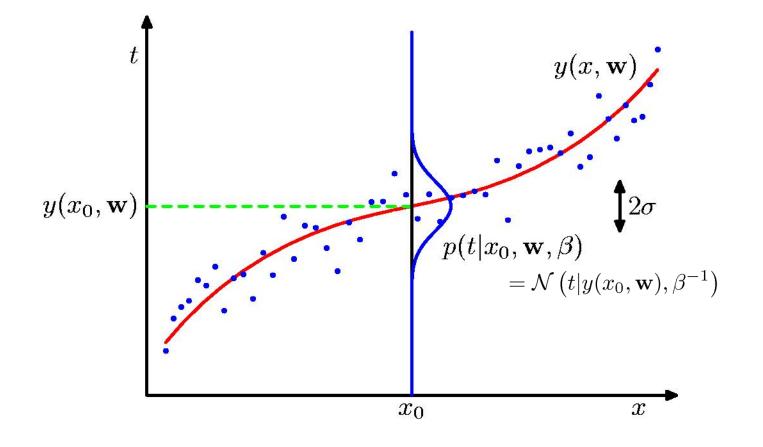
$$p(\mu|\mathbf{x}) \propto p(\mu)p(\mathbf{x}|\mu)$$

$$= \left[p(\mu)\prod_{n=1}^{N-1}p(x_n|\mu)\right]p(x_N|\mu)$$

$$\propto \mathcal{N}\left(\mu|\mu_{N-1},\sigma_{N-1}^2\right)p(x_N|\mu)$$

The posterior obtained after observing N -1 data points becomes the prior when we observe the Nth data point.

Curve Fitting Re-visited



Maximum Likelihood

$$p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = \prod_{n=1}^{N} \mathcal{N}\left(t_n | y(x_n, \mathbf{w}), \beta^{-1}\right)$$

$$\mathbf{Data} \quad \begin{array}{l} \mathbf{x} = (x_1, \dots, x_N)^{\mathrm{T}} \\ \mathbf{t} = (t_1, \dots, t_N)^{\mathrm{T}} \end{array}$$

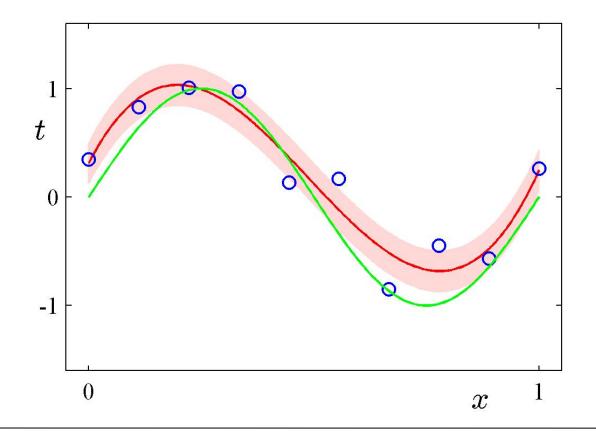
$$\ln p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = -\underbrace{\frac{\beta}{2} \sum_{n=1}^{N} \left\{y(x_n, \mathbf{w}) - t_n\right\}^2}_{\beta E(\mathbf{w})} + \frac{N}{2} \ln \beta - \frac{N}{2} \ln(2\pi)$$

Determine \mathbf{w}_{ML} by minimizing sum-of-squares error, $E(\mathbf{w})$. Determine also the precision parameter (inverse variance):

$$\frac{1}{\beta_{\rm ML}} = \frac{1}{N} \sum_{n=1}^{N} \{ y(x_n, \mathbf{w}_{\rm ML}) - t_n \}^2$$

Predictive Distribution

$$p(t|x, \mathbf{w}_{\mathrm{ML}}, \beta_{\mathrm{ML}}) = \mathcal{N}\left(t|y(x, \mathbf{w}_{\mathrm{ML}}), \beta_{\mathrm{ML}}^{-1}\right)$$



MAP: A Step towards Bayes

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I}) = \left(\frac{\alpha}{2\pi}\right)^{(M+1)/2} \exp\left\{-\frac{\alpha}{2}\mathbf{w}^{\mathrm{T}}\mathbf{w}\right\}$$

$$p(\mathbf{w}|\mathbf{x}, \mathbf{t}, \alpha, \beta) \propto p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta)p(\mathbf{w}|\alpha)$$

$$\beta \widetilde{E}(\mathbf{w}) = \frac{\beta}{2} \sum_{n=1}^{N} \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{\alpha}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

Determine \mathbf{w}_{MAP} by minimizing regularized sum-of-squares error, $\widetilde{E}(\mathbf{w})$.

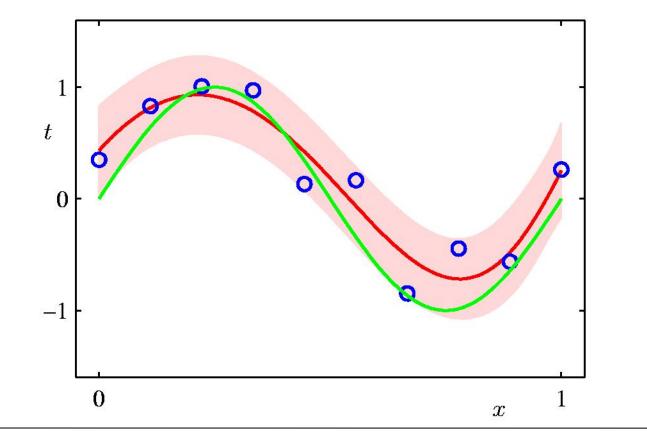
Bayesian Curve Fitting

$$p(t|x, \mathbf{x}, \mathbf{t}) = \int p(t|x, \mathbf{w}) p(\mathbf{w}|\mathbf{x}, \mathbf{t}) \, \mathrm{d}\mathbf{w} = \mathcal{N}\left(t|m(x), s^2(x)\right)$$

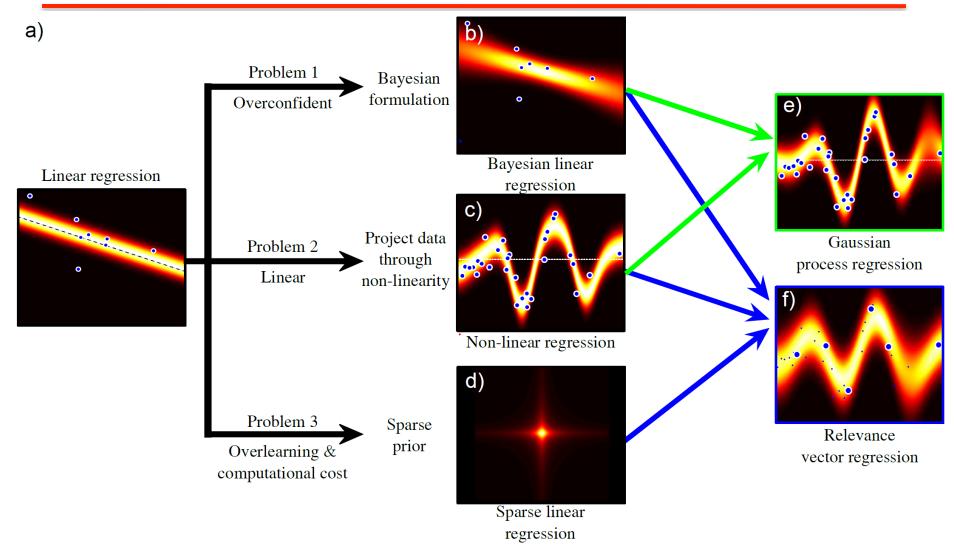
$$m(x) = \beta \phi(x)^{\mathrm{T}} \mathbf{S} \sum_{n=1}^{N} \phi(x_n) t_n \qquad s^2(x) = \beta^{-1} + \phi(x)^{\mathrm{T}} \mathbf{S} \phi(x)$$
$$\mathbf{S}^{-1} = \alpha \mathbf{I} + \beta \sum_{n=1}^{N} \phi(x_n) \phi(x_n)^{\mathrm{T}} \qquad \phi(x_n) = \left(x_n^0, \dots, x_n^M\right)^{\mathrm{T}}$$

Bayesian Predictive Distribution

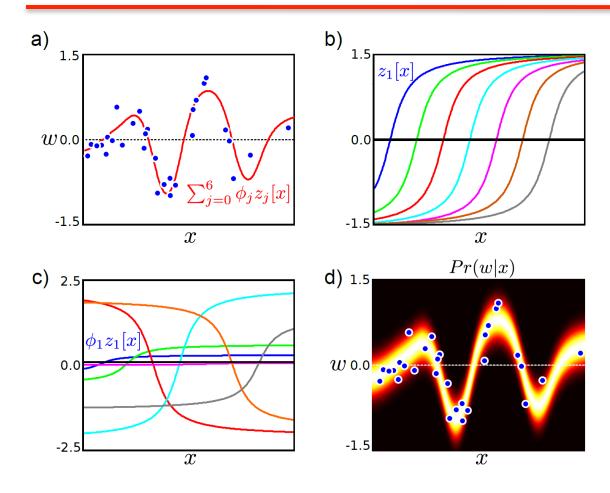
$$p(t|x, \mathbf{x}, \mathbf{t}) = \mathcal{N}\left(t|m(x), s^2(x)\right)$$



Regression Models

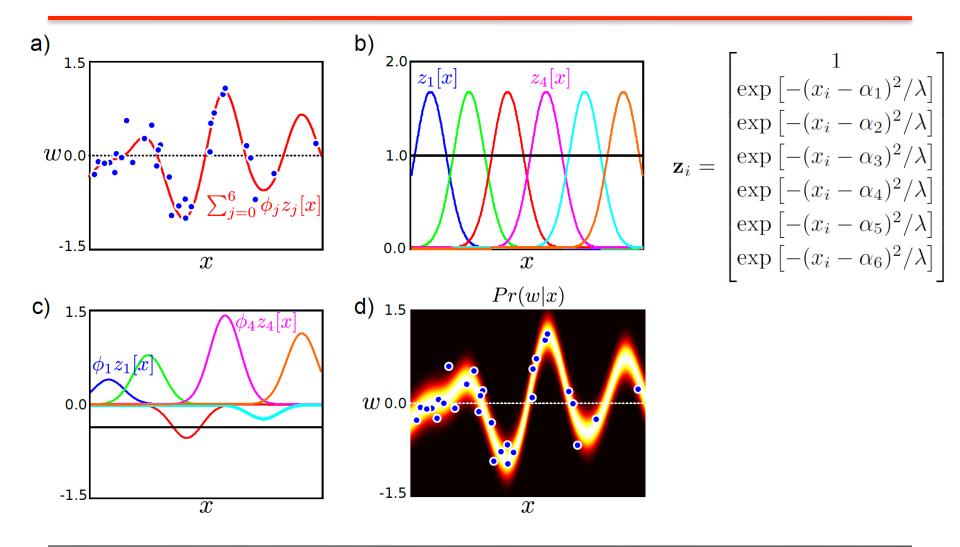


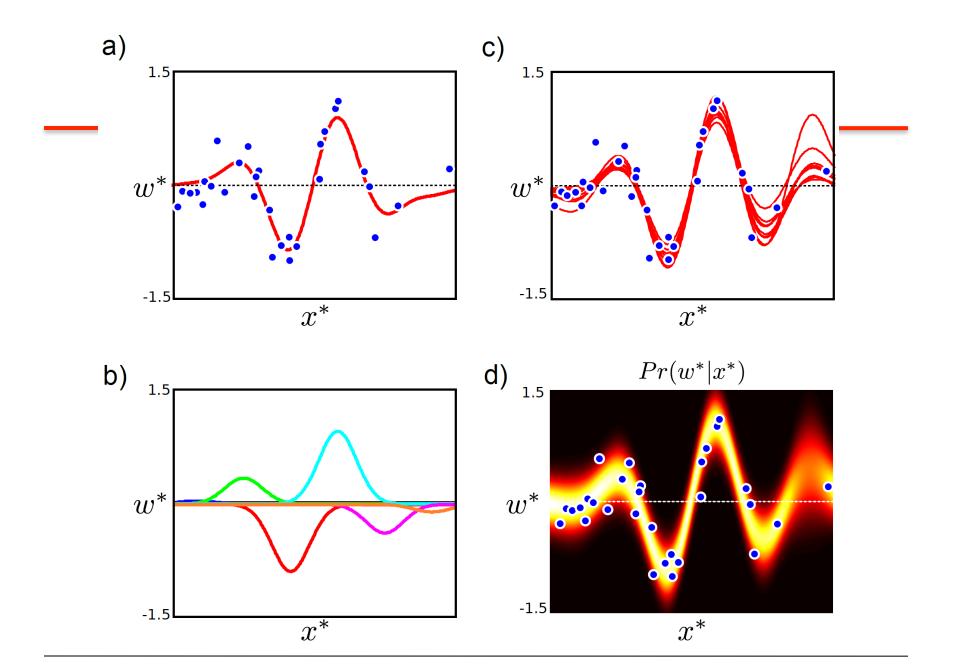
Arc Tan Functions



$$\mathbf{z}_{i} = \begin{bmatrix} \arctan[\lambda x_{i} - \alpha_{1}] \\ \arctan[\lambda x_{i} - \alpha_{2}] \\ \arctan[\lambda x_{i} - \alpha_{3}] \\ \arctan[\lambda x_{i} - \alpha_{4}] \\ \arctan[\lambda x_{i} - \alpha_{5}] \\ \arctan[\lambda x_{i} - \alpha_{5}] \\ \arctan[\lambda x_{i} - \alpha_{6}] \\ \arctan[\lambda x_{i} - \alpha_{7}] \end{bmatrix}$$

Radial basis functions





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RBF Kernel Fits

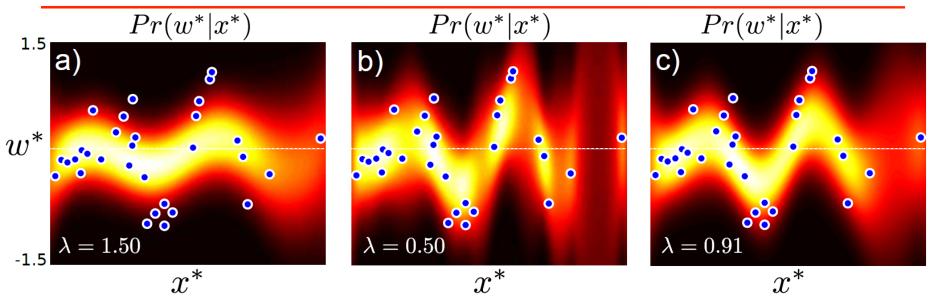


Figure 8.9 Gaussian process regression using an RBF kernel a) When the length scale parameter λ is large, the function is too smooth. b) For small values of the length parameter the model does not successfully interpolate between the examples. c) The regression using the maximum likelihood length scale parameter is neither too smooth nor disjointed.

$$k[\mathbf{x}_i, \mathbf{x}_j] = \exp\left[-0.5\left(\frac{\mathbf{x}_i - \mathbf{x}_j}{\lambda}\right)^2\right]$$