Bayesian Model Comparison (1)

How do we choose the 'right' model?

Assume we want to compare models M_i , i=1, ...,L, using data D; this requires computing

$$p(\mathcal{M}_i|\mathcal{D}) \propto p(\mathcal{M}_i)p(\mathcal{D}|\mathcal{M}_i).$$

Posterior

Prior

Model evidence or *marginal likelihood*

Bayes Factor: ratio of evidence for two models

 $\frac{p(\mathcal{D}|\mathcal{M}_i)}{p(\mathcal{D}|\mathcal{M}_j)}$

Bayesian Model Comparison (2)

Having computed $p(M_i j D)$, we can compute the predictive (mixture) distribution $p(t|\mathbf{x}, D) = \sum_{i=1}^{L} p(t|\mathbf{x}, M_i, D) p(M_i | D).$

A simpler approximation, known as *model selection*, is to use the model with the highest evidence.

Bayesian Model Comparison (3)

For a model with parameters W, we get the model evidence by marginalizing over W

$$p(\mathcal{D}|\mathcal{M}_i) = \int p(\mathcal{D}|\mathbf{w}, \mathcal{M}_i) p(\mathbf{w}|\mathcal{M}_i) \,\mathrm{d}\mathbf{w}.$$

Note that

$$p(\mathbf{w}|\mathcal{D}, \mathcal{M}_i) = \frac{p(\mathcal{D}|\mathbf{w}, \mathcal{M}_i)p(\mathbf{w}|\mathcal{M}_i)}{p(\mathcal{D}|\mathcal{M}_i)}$$

Bayesian Model Comparison (4)



Bayesian Model Comparison (5)

Taking logarithms, we obtain

$$\ln p(\mathcal{D}) \simeq \ln p(\mathcal{D}|w_{\text{MAP}}) + \ln \left(\frac{\Delta w_{\text{posterior}}}{\Delta w_{\text{prior}}}\right)$$
Negative

With M parameters, all assumed to have the same ratio $\Delta w_{\rm posterior}/\Delta w_{\rm prior}$, we get

$$\ln p(\mathcal{D}) \simeq \ln p(\mathcal{D}|\mathbf{w}_{\text{MAP}}) + M \ln \left(\frac{\Delta w_{\text{posterior}}}{\Delta w_{\text{prior}}}\right)$$

Negative and linear in M.

Bayesian Model Comparison (6)

Matching data and model complexity



The Evidence Approximation (1)

The fully Bayesian predictive distribution is given by

$$p(t|\mathbf{t}) = \iiint p(t|\mathbf{w},\beta)p(\mathbf{w}|\mathbf{t},\alpha,\beta)p(\alpha,\beta|\mathbf{t})\,\mathrm{d}\mathbf{w}\,\mathrm{d}\alpha\,\mathrm{d}\beta$$

but this integral is intractable. Approximate with

$$p(t|\mathbf{t}) \simeq p\left(t|\mathbf{t}, \widehat{\alpha}, \widehat{\beta}\right) = \int p\left(t|\mathbf{w}, \widehat{\beta}\right) p\left(\mathbf{w}|\mathbf{t}, \widehat{\alpha}, \widehat{\beta}\right) \, \mathrm{d}\mathbf{w}$$

where $(\widehat{\alpha}, \widehat{\beta})$ is the mode of $p(\alpha, \beta | \mathbf{t})$, which is assumed to be sharply peaked; a.k.a. *empirical Bayes, type II* or *generalized maximum likelihood,* or *evidence approximation*.

The Evidence Approximation (2)

From Bayes' theorem we have

 $p(\alpha, \beta | \mathbf{t}) \propto p(\mathbf{t} | \alpha, \beta) p(\alpha, \beta)$

and if we assume $p(\alpha,\beta)$ to be flat we see that

$$p(\alpha, \beta | \mathbf{t}) \propto p(\mathbf{t} | \alpha, \beta)$$

= $\int p(\mathbf{t} | \mathbf{w}, \beta) p(\mathbf{w} | \alpha) \, \mathrm{d}\mathbf{w}.$

General results for Gaussian integrals give

$$\ln p(\mathbf{t}|\alpha,\beta) = \frac{M}{2}\ln\alpha + \frac{N}{2}\ln\beta - E(\mathbf{m}_N) + \frac{1}{2}\ln|\mathbf{S}_N| - \frac{N}{2}\ln(2\pi).$$

The Evidence Approximation (3)

Example: sinusoidal data, M th degree polynomial, $\alpha = 5 \times 10^{-3}$



Regression vs. Classification

Regression:

$$x \in [-\infty, \infty], t \in [-\infty, \infty]$$

Classification:

 $x\in [-\infty,\infty], t\in \{0,1\}$

Minimum Misclassification Rate



Minimum Misclassification Rate



We are free to choose the decision rule that assigns each point x to one of the two classes.

To minimize integrand: $p(\mathbf{x}, C_k) = p(C_k | \mathbf{x}) p(\mathbf{x})$ must be small Assign x to class for which the posterior $p(C_k | \mathbf{x})$ is larger!

Three strategies

1. Modeling the class-conditional density for each class C_k , and prior, then use Bayes

$$p(\mathcal{C}_k | \mathbf{x}) = \frac{p(\mathbf{x} | \mathcal{C}_k) p(\mathcal{C}_k)}{p(\mathbf{x})}$$

- 2. First solve the inference problem of determining the posterior class probabilities $p(C_k|x)$, and then subsequently use decision theory to assign each new x to one of the classes
- Find discriminant function that directly maps x to class label

Class-conditional density vs. posterior



Several dimensions



Several dimensions



Projecting data down to one dimension $y = \mathbf{w}^{\mathrm{T}} \mathbf{x}$

But how?



Define class means

$$\mathbf{m}_1 = \frac{1}{N_1} \sum_{n \in \mathcal{C}_1} \mathbf{x}_n,$$

$$\mathbf{m}_2 = \frac{1}{N_2} \sum_{n \in \mathcal{C}_2} \mathbf{x}_n$$

Try maximize

$$m_2 - m_1 = \mathbf{w}^{\mathrm{T}}(\mathbf{m}_2 - \mathbf{m}_1)$$



Instead, consider: ratio of between class variance to within class variance

$$J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}$$

With $s_k^2 = \sum_{n \in \mathcal{C}_k} (y_n - m_k)^2$

Called Fisher criterion. Maximize it!

Maximizing the Fisher Criterion we obtain

$$\mathbf{w} \propto \mathbf{S}_{\mathrm{W}}^{-1}(\mathbf{m}_2 - \mathbf{m}_1)$$

with the total within class covariance

$$\mathbf{S}_{\mathrm{W}} = \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \mathbf{m}_1) (\mathbf{x}_n - \mathbf{m}_1)^{\mathrm{T}} + \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \mathbf{m}_2) (\mathbf{x}_n - \mathbf{m}_2)^{\mathrm{T}}$$

This is called Fisher's linear discriminant

Fisher's linear discriminant

Fisher Criterion

1

12

$$\mathbf{w} \propto \mathbf{S}_{\mathrm{W}}^{-1}(\mathbf{m}_2 - \mathbf{m}_1)$$
 $J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}$



Least squares for classification fails



Use logistic regression instead!

Bernoulli Distribution



$$Pr(x = 0) = 1 - \lambda$$

 $Pr(x = 1) = \lambda$.
or
 $Pr(x) = \lambda^x (1 - \lambda)^{1-x}$
For short we write:
 $Pr(x) = \operatorname{Bern}_x[\lambda]$

Bernoulli distribution describes situation where only two possible outcomes y=0/y=1 or failure/success

```
Takes a single parameter \lambda \in [0, 1]
```

Logistic Regression

Consider two class problem.

- Choose Bernoulli distribution over world.
- Make parameter λ a function of x

$$Pr(w|\phi_0, \phi, \mathbf{x}) = \operatorname{Bern}_w[\operatorname{sig}[a]]$$

Model activation with a linear function

$$a = \phi_0 + \phi^T \mathbf{x}$$

creates number between $[-\infty, \infty]$. Maps to $[0, 1]$ with $\operatorname{sig}[a] = rac{1}{1 + \exp[-a]}$



Learning by standard methods (ML,MAP, Bayesian) Inference: Just evaluate Pr(w|x)

Neater Notation

$$Pr(w|\phi_0, \phi, \mathbf{x}) = \operatorname{Bern}_w[\operatorname{sig}[a]]$$

To make notation easier to handle, we

• Attach a 1 to the start of every data vector

$$\mathbf{x}_i \leftarrow \begin{bmatrix} 1 & \mathbf{x}_i^T \end{bmatrix}^T$$

- Attach the offset to the start of the gradient vector $\boldsymbol{\varphi}$

$$\boldsymbol{\phi} \leftarrow [\phi_0 \quad \boldsymbol{\phi}^T]^T$$

New model:

$$Pr(w|\boldsymbol{\phi}, \mathbf{x}) = \operatorname{Bern}_{w} \left[\frac{1}{1 + \exp[-\boldsymbol{\phi}^{T}\mathbf{x}]} \right]$$

Logistic regression



Computer vision: models, learning and inference. ©2011 Simon J.D. Prince